Autonics

Temperature/Humidity Transducer **THD SERIES**

INSTRUCTION MANUAL



Thank you for choosing our Autonics product. Please read the following safety considerations before use.

■ Safety Considerations

**Please observe all safety considerations for safe and proper product operation to avoid hazards. x symbol represents caution due to special circumstances in which hazards may occur.

▲ Warning Failure to follow these instructions may result in serious injury or death.

▲ Caution Failure to follow these instructions may result in personal injury or product damage

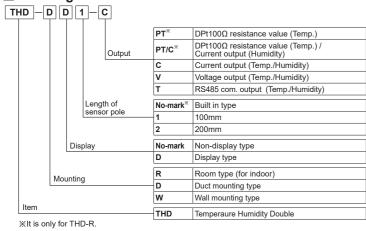
⚠ Warning

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipmen ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in fire, personal injury, or economic loss. 2. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire.
- 3. Check 'Connections' before wiring. Failure to follow this instruction may result in fire
- 1. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire

▲ Caution

- 1. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 2. Use dry cloth to clean the unit, and do not use water or organic solvent
- Failure to follow this instruction may result in fire.
- 3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion.
- 1. Keep metal chip, dust, and wire residue from flowing into the unit. Failure to follow this instruction may result in fire or product damage.

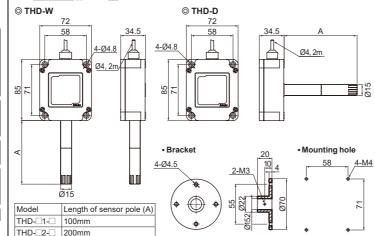
Ordering Information



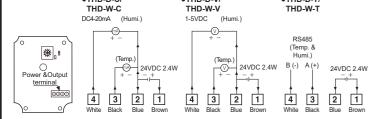
Specifications THD-D□-THD-DD . THD_R_PT/C Power supply Permissible voltage range 24VDC: Power consumption Max. 2.4W Sensor type 7Segment LED Display type Each 3 digits for Display digit W6.2×H10.0mm Character size Measuring Temp. range Humidity -19.9 to 60.0°0 0.0 to 99.9%RH (THD-R is required to attend for using over 90%RH) ±1°C (at room temp.) Typ. ±2%RH (10 to 90%RH, at room temp.) ±3%RH (30 to 70%RH, at room **Humidity** temp.), ±4%RH (10 to 90%RH) ※Max. ±2.5%RH (TCR: 3850ppm/°C) DC4-20mA (allowable impedance: max. 600Ω), DC4-20mA Outpu RS485 communication (Modbus RTU) mpedance: max. 600Ω) Sampling period 0.5 sec Min. 100MΩ (at 500VDC megger) 500VAC 50/60Hz for 1 minute ±0.3kV the square wave noise (pulse width: 1µs) by the noise simulator 0.75mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 1 hour 0.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 10 minutes Malfunction 300m/s² (approx. 30G) in each X, Y, Z direction for 3 times Mechanical 100m/s² (approx. 10G) in each X, Y, Z direction for 3 times -20 to 60°C, storage: -20 to 60°C ment Ø4mm, 4-wire, length: 2m (AWG22, Core diameter: 0.08mr number of cores: 60, insulation Cable out diameter: Ø1.25mm) C €, [§ (only for THD-□-T model) Approx. 98g (approx. 55g) Approx. 415g (approx. 160g)

| Weight: | In Profession | In

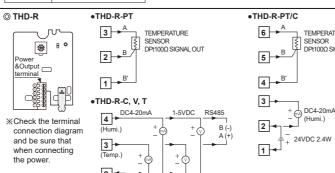
© THD-R 2-M3 /



Terminal Connection ⊚ THD-D/THD-W •THD-D-V/ •THD-D-T/



*The above specifications are subject to change and some models may be discontinued without notice. Be sure to follow cautions written in the instruction manual and the technical descriptions (catalog, homepage).



24VDC 2.4W

■ Case Detachment

⊚ THD-R

Parity bit

Unfasten the bolt on the bottom of the product, separate the case from it



© THD-D/THD-W Unfasten 4 bolts on the top of the product, separate



Current Output

It transmits current temperature/humidity to other devices (PC, recorder, etc.) and outputs DC4-20mA It outputs DC4mA at -19.9°C of temperature and 0%RH of humidity, DC20mA at 60°C of temperature and 99.9%RH of humidity. The temperature and humidity output are separated and the resolution is divisible by 1,000.

Voltage Output

It transmits current temperature/humidity to other devices (PC, recorder, etc.) and outputs 1-5VDC. It outputs 1VDC at -19.9°C of temperature and 0%RH of humidity, 5VDC at 60°C of temperature and 99.9%RH of humidity. The temperature and humidity output are separated and the resolution is divisible by 1,000.

■ DPt 100Ω Resistance Value Output

It transmits current temperature to other devices (recorder, thermome and 119.40Ω at 50°C. (Temperature coefficient (TCR)=3850ppm/°C) ometer, etc.). It outputs 100Ω at 0°C

■ RS485 Communication Output

It is output transmit current temperature and humidity to other devices (PC, recorder, etc.) by communication.
Interface

illellace	
Comm. protocol	Modbus RTU
Connection type	RS485
Application standard	Compliance with EIA RS485
Max. connection	31 units (address: 01 to 31)
Synchronous method	Asynchronous
Comm. method	Two-wire half duplex
Comm. distance	Max. 800m
Comm. speed	1200 to 115200bps (selectable)
Stort hit	1 bit (fixed)

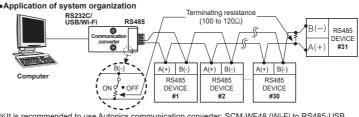
1-bit (fixed)

XIt is not possible to change parameter related to communication of THD under the communication wth high order system. (At communication status, THD and

upper system are available to change the address.)

 Match the parameter of THD communication to be same as the high order system.

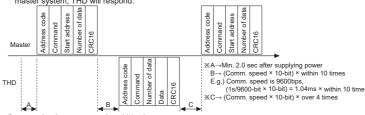
XIt is not allowed to set overlapping communication address at the same communication line.



It is recommended to use Autonics communication converter; SCM-WF48 (Wi-Fi to RS485-USB wireless communication converter, sold separately), SCM-US481 (USB to RS485 converter, sold separately), SCM-US481 (USB to RS485 converter, sold separately). Please use twisted pair wire, which is suitable for RS485 communication, for SCM-WF48, SCM-US48I and SCM-38I.

Ordering of communication control

1. The communication method is Modbus RTU.
2. After 2.0 sec being supplied the power into master system, it is able to start communication.
3. The initial communication is started by master system. When a command comes out from the master system, THD will respond.



Communication command and block

The format of query and response

____ TEMPERATURE

DC4-20mA

SENSOR DPt100Ω SIGNAL OUT

Query					
Address code	Command	Start address	Number of data	CRC16	
	Calculation	range of CRC1	16		

①Address code: This address code is for identifying THD by master system and able to set within range of 01 to 31.

nmand: Read command for input register

③ Start address: The start address of input register to read (start address). It is available to select 0000 and 0001 for start address. 16-bit data in the address 0000 indicates temperature value, 16bit data in the address 0001 indicates humidity value, (refer to Modbus Mapping table.)

Number of data: The number of 16-bit data from start address (no. of Points). When start address is 0000, it is available to read 2 of 16-bit data, or when start address is 0001, it is available to read

©CRC16: Checksum for checking the whole frame and it is used for more reliable transmit/receive

response					
Address code	Command	Number of data	Temperature data	Humidity data	CRC16
_					

①Address code: This address code is for identifying THD by master system and able to set within

© Command: A response for read command of input register

Number of data: The number of 8-bit data to send from start address (no. of bytes). When start address is 0000, it is available to read 4 of 8-bit data, or when start address is 0001, it is available

Temperature data: This is the value of 16-bit. To get a current temperature value, divide read value

E.g. When read data is 0x09B0, decimal value is 2480, the current value is 2480/100=24.80°C. ©Humidity data: This is the value of 16-bit. To get a current humidity value, divide read value by 100. E.g.)When read data is 0×0B68, decimal value is 2920, the current value is 2920/100=29.20%RH. ©CRC16: Checksum for checking the whole frame

Application for communication command

(Query): Address code (01), Start address (0000), The number of 16-bit data to read (2), CRC16 (0×71CB | 00 | 00 | 00 | 02 | 71 | Start address | Amount of data | CRC16 |

Command Start address
High Lo Low High Low

(Response): Address code (01), The number of 8-bit data to read (4), Temperature (0×09B0),

Humidity (0×0B68), CRC16 (0×94DE)							,	
)1	04	04	09	B0	0B	68	94	DE
Address	Reponse	Number	Temperature data		Humidity d	ata	CRC16	
ode	command	of data	High	Low	High	Low	High	Low

Error processing (Slave → Master)

. Not supported command XX Exception code

Set a received the highest bit and send it to response command and exception code 01. 2. The start address of gueried data is inconsistent with the transmittable address or the requested

number of data is bigger than the transmittable address.

Exception code CRC16

Set a received the highest bit and send it to response command and exception code 02. Modbus Mapping Table

30001 (0000) Temperature value Temperature value × 0.01 30002 (0001) Humidity value Humidity value × 0.01

2. Set SW1 to 0 and supply the power.
3. Operation indicator LED is flashing.
4. Set a communication speed after choosing SW1 within the

Setting communication speed <Setting table for Turn off the power of the unit

communication speed>

SW1 | Comm. speed (bps) 5 | 19200 speed (bps) 2400 38400 57600

After setting a communication speed, the LED will be ON. At the moment turn OFF the power. *Factory default communication speed is 9600bps

range 1 to 8, and hold it for 3 sec.

Setting communication address

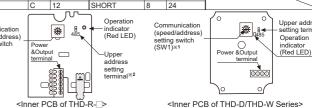
1. Set upper address setting terminal and setting switch (SW1) to the desired address and supply the power

2. The communication address is changed automatically.

«Factory default communication address is 01.

(SW1: 1, Upper address setting terminal: OPEN)

5								
Upper address setting terminal	SW1	Address	Upper address setting terminal	SW1	Address	Upper address setting terminal	SW1	Address
OPEN	1	01	OPEN	D	13	SHORT	9	25
OPEN	2	02	OPEN	E	14	SHORT	Α	26
OPEN	3	03	OPEN	F	15	SHORT	В	27
OPEN	4	04	SHORT	0	16	SHORT	С	28
OPEN	5	05	SHORT	1	17	SHORT	D	29
OPEN	6	06	SHORT	2	18	SHORT	E	30
OPEN	7	07	SHORT	3	19	SHORT	F	31
OPEN	8	08	SHORT	4	20			
OPEN	9	09	SHORT	5	21	1 \		
OPEN	Α	10	SHORT	6	22	1	_	
OPEN	В	11	SHORT	7	23	1		_
OPEN	С	12	SHORT	8	24	1		
,		7 ///) , <i>i</i>			70	~	



*1: Only when communication setting, remove the case cover and adjust communication setting switch to set address and communication speed.

**2: Short terminal as upper address setting terminal, the lower address setting is available

■ Comprehensive Device Management Program [DAQMaster]

DAQMaster is comprehensive device management program. It is available for temperature and humid For more information, please refer to the DAQMa

user manual. Visit our web site (www.autonics.com) to downloa

DAQMaster program.

	Itelli	IVIII III III SPECIII CAUOTIS
nt ditv	System	IBM PC compatible computer with
	System	Pentium III or above
uity	Operations	Windows 98/NT/XP/Vista/7/8/10
ter	Memory	256MB+
	Hard disk	1GB+ of available hard disk space
ad	VGA	Resolution: 1024×768 or higher
	Others	RS232C serial port (9-pin), USB port
		•

Cautions during Use

. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents. Keep away from high voltage lines or power lines to prevent inductive noise

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply

device.

Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise

Do not touch TDH-W/D sensor part at the bottom of the sensor pole by hands. It may cause malfunction.

THD-R must be installed on the wall.

It may cause malfunction.

8. Make a required space around the unit for radiation of heat.
For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.

10. Do not wire to terminals which are not used.

This unit may be used in the following environments.

①Indoors (in the environment condition rated in 'Specifications') ②Altitude max. 2,000m ③Pollution degree 2

■ Major Products

ner Motors/Drivers/Motion Controllers nic/Logic Panels Network Devices Marking System (Fiber, Co₂, Nd: yag) Welding/Cutting System

Autonics Corporation ■ HEADQUARTERS

DRW161011AC