### **Autonics**

**Multi-Channel Modular Type High Performance Temperature Controller [Control Module]** 

# TMH2/TMH4 Series





Thank you for choosing our Autonics product. Please read the following safety considerations before use.

#### ■ Safety Considerations

\*\*Please observe all safety considerations for safe and proper product operation to avoid hazards.

★★ symbol represents caution due to special circumstances in which hazards may occur.

**⚠Warning** Failure to follow these instructions may result in serious injury or death. ▲Caution Failure to follow these instructions may result in personal injury or product damage

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1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, fire, or economic loss

- 2. Install on a device panel to use.
- Failure to follow this instruction may result in fire. 3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.
- 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire
- 5. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

  Caution

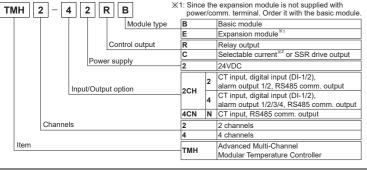
1. When connecting the power input and relay output, use AWG 20 (0.50mm<sup>2</sup>) cable or over and tighten the terminal screw with a tightening torque of 0.74 to 0.90Nm.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to

16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90Nm. Failure to follow this instruction may result in fire or malfunction due to contact failure.

2. Use the unit within the rated specifications.

- Failure to follow this instruction may result in fire or product damage 3. Use dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire.
- 4. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight radiant heat, vibration, impact, or salinity may be present.
- Failure to follow this instruction may result in explosion or fire 5. Keep metal chip, dust, and wire residue from flowing into the unit. Failure to follow this instruction may result in fire or product damage.
- Ordering Information





- number of connected expansion module.

  \*\*2. ②At room temperature (23°C±5°C)

  · Thermocouple K, J, N, E below ·100°C, L, U, PLII and RTD Cu50Ω, DPt50Ω

  · (PV ±0.3% or ±2°C, higher one) ±1-digit

  · Thermocouple C, G and R, S below 200°C: (PV ±0.3% or ±3°C, higher one) ±1-digit

  · Thermocouple B below 400°C: (there is no accuracy standards.

  ③Out of room temperature range

  · RTD Cu50Ω, DPt50Ω: (PV ±0.5% or ±3°C, higher one) ±1-digit

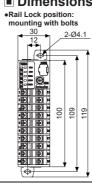
  · Thermocouple R, S, B, C, G: (PV ±0.5% or ±5°C, higher one) ±1-digit Others blow -100°C: within ±5°C

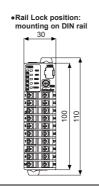
  \*\*3. If the control output is set to current output, the heater current value monitoring function through the CT input terminal of the control module is not available.

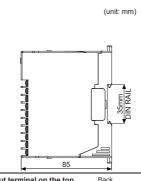
  \*\*4. The weight includes packaging, The weight in parenthesis is for unit only.

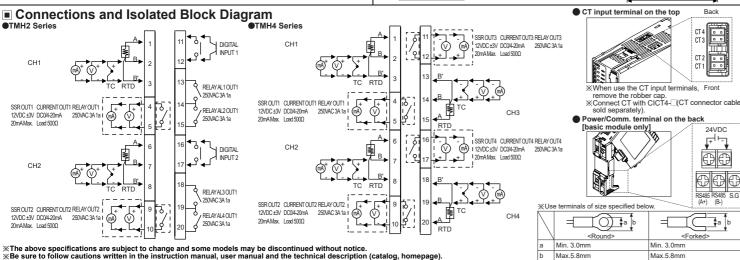
  \*\*Environment resistance is rated at no freezing or condensation.

### Dimensions

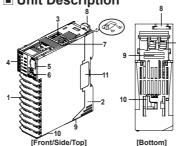








# Unit Description



 Input/Output terminal
 For specific information about terminal formation, please refer to '
 Connections and Isolated Block 2. Power/Comm. terminal

[basic module only]
Supplies power to both basic control/expansio module and communicates with one or more

3. CT input termina When using the CT input terminal, remove the rubber cap and connect CT in the same direction with right

image.
Connect CT with CICT4—
(CT connector cable, sold separately).

\*When connecting CT connector and
CT input terminal,

CT input terminal,

\*CT input te

Front

CH1 (red)		icato 12 Se					align the	concave p	art (凹) and	d the conv	ex part (凸)
CH1 (red)	Indica	ator	_	Status				N.O.(Nom	nally Open)		
PWR         LED 1         CH2 (red)         —         ON         Flash         —           CH 1 AL1         (red)         (oN <sup>±4</sup> OFF         OFF           (red)         (oN <sup>±5</sup> OFF         OFF           CH2 AL2         (yellow)         Flash (4,800bps)         Module comm. status <sup>™5</sup>	LED 1	LED 2		PWR (green)**3		ON	ON				
CH   AL1   (red)   (red)   (red)   (red)   (red)   (vellow)   (yellow)   (Jash (4,800bps)   Module comm. status   (status   vellow)   (status		_	LED 1	CH1 (red)	]-	ON	Flash				
CH1 AL1 (red) ON* OFF OFF OFF OFF (yellow) Flash (4,800bps) Module comm. status **5	PWR			CH2 (red)		ON	Flash	l <b>—</b>			
CH2 AL2 (yellow) Flash (4,800bps) Module comm. status <sup>X6</sup>	CILI			(red)			OFF				
		ALI		(red)		ON <sup>*5</sup>	OFF	1			
		AL2 AL3	LED 2	(yellow)	Flash (4,800bps)	Module c	omm. stat	tus <sup>*6</sup>			
AL1 (yellow)   Flash (9,600bps)   —   OFF   ON   OFF   ON				AL1 (yellow)	Flash (9,600bps)	<b> </b> —	<b> </b>	OFF	ON	OFF	ON
AL3 LED 2 AL2 (yellow) Flash (19,200bps) — OFF ON OFF ON				AL2 (yellow)	Flash (19,200bps)	_	_	OFF	ON	OFF	ON
AL3 (yellow) Flash (38,400bps) — OFF ON OFF ON				AL3 (yellow)	Flash (38,400bps)	_	_	OFF	ON	OFF	ON
AL4 (yellow) Flash (115,200bps) — OFF ON OFF ON		AL4		AL4 (yellow)	Flash (115,200bps)	_	_	OFF	ON	OFF	ON

TMH4 Series									
Indica	ator	_	Status	Initial power ON*1	Control output	Auto tuning <sup>**2</sup>			
LED 1	LED 2	LED 1	PWR (green)*3		ON	ON			
PWR CH1 CH2			CH1 (red)		ON	Flash			
			CH2 (red)	l <b>—</b>	ON	Flash			
			CH3 (red)		ON	Flash			
			CH4 (red)		ON	Flash			
			(yellow)	Flash (4,800bps)	Module comm.	status <sup>*6</sup>			
			(yellow)	Flash (9,600bps)					
CH 3		LED 2	(yellow)	Flash (19,200bps)	_				
			(yellow)	Flash (38,400bps)	_	_			
CH 4			(yellow)	Flash (115,200bps)	<b> </b>	_			

- #1: At the moment when power is on, the indicator of set communication speed flashes for 5 sec.

  #2: Indicator of the channel, which is in the process of auto-tuning, flashes at 1 sec interval.

  #3: When communicating with external device, PWR indicator flashes.

  #4: Turns on, when CH1 outputs cooling control in the heating&cooling control method.

  #5: Turns on, when CH2 outputs cooling control in the heating&cooling control method.

  #6: Displays communication status in control output, auto-tuning or operating RUN mode.

  ON: normal / flash: abnormal / OFF: not communicating

  5. PC loader port: PC loader port supports serial communication between single module and PC.

  It needs EXT-US (converter cable)+SCM-US (USB/Serial converter, sold separately) for communicating.

  6. Communication address setting switch (SW1): Set the communication address.

  If changing the communication address by setting switch, use the flat head driver which is 2mm size or plastic driver. If not, it may cause product damage.
- driver. If not, it may cause product damage.

  7. Communication address group switch (SW2): When setting the communication address over 16, select +16.

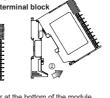
  8. Rail lock. Rail lock helps installing the device to DIN rail or with bolts.

  9. Lock lever: Lock lever holds module body and base tightly.

  10. Module lock connecter hole: When connect modules, insert module lock connector in the hole in order to enhance coherence between modules.
- 11. END cover: When connect modules, remove END cover in order to connect expansion connector

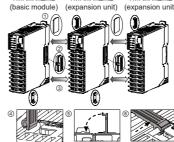
#### Installation





Pull the body of the module and open up. wWhen connecting base terminal block, align the upper concave part (凹) of the body and the upper convex part (凸) of the base. If the upper parts are not align correctly, it may damage to the inner connector

TMHI-12 E



Insert expansion connector.Put all together tightly (max. 31 units).

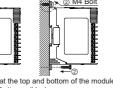
1) Insert module lock connector. ©Push module lock connector and insert in lock connector hole of another module on the side.

(a) Push module lock connector to the lock direction Supply adequate power for power input specifications and overall capacity

(Max. power when connecting 32 modules





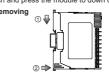


 Pull the rail lock at the top and bottom of the module Insert bolts and fix it on rail lock (fixing torque is 0.5 to 0.9N·m.)

# 4. Mounting on DIN rail 4.4.1 Installing



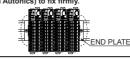
②Push and press the module to down direction



Press the module down ②Pull the module body forward. XInstall the module vertically.



XUse end plates (sold separately, not available nics) to fix firmly



## ■ Communication Setting

It is for parameter setting and monitoring via ex

 Interface 4800, 9600 (default), 19200, 38400, 115200 bps Connection type RS485 EIA RS485 Compliance with 1-bit (fixed) Start bit standard 32 units (address: 01 to 32) (in case connecting TMHC module 16 units (address: 01 to 16)) Synchronous method Asynchronous
Comm. method Two-wire half duplex None (default), Odd, Even 1-bit, 2-bit (default) Comm. effective range Max. 800m

Application of system organization

XOnly for RS485 communication output model. RS232C/ B (-) RS485 DEVICE 0 A(+)B(-) A(+)B(-) A(+)B(-) A (+) #31 RS485 DEVICE #2 DEVICE

(It is recommended to use Autonics communication converter, SCM-WF48 (Wi-Fi to RS485-USB wireless communication converter, sold separately), SCM-US481 (USB to RS485 converter, sold separately), SCM-US481 (USB to Serial converter, sold separately), SCM-US40 (USB to Serial converter, sold separately). Please use twisted pair wire, which is suitable for RS485 communication, for SCM-WF48, SCM-US481 and SCM-381.

Set the communication address setting

Set the communication address with the communication address setting switch (SW1) and communication address group switch (SW2) (default: [SW1] 1, [SW2] +0).

SW1		0														
	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
+0 +16	16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
<b>■</b> +0 +16	32	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31

Caution for communication address setting
 After changing communication address via the power/comm. terminal, reboot the device.

### Comprehensive Device Management Program[DAQMaster]

DAQMaster is a comprehensive device management software for setting paramete processes. DAQMaster can be downloaded from our website at www.autonics.com

Minimum specifications					
IBM PC compatible computer with Pentium III or above					
Windows 98/NT/XP/Vista/7/8/10					
256MB+					
1GB+ of available hard disk space					
Resolution: 1024×768 or higher					
RS232C serial port (9-pin), USB port					

#### Error Display

Indicator Status	Input error <sup>*1</sup>	Remote SV error <sup>**2</sup>								
	ON (red)	ON (green)								
CH□ <sup>×3</sup>	Flash (red)	Flash (red)								

- X1: Input error: input value is below the input range (LLLL) / input value exceeds input range (HHHH) / input sensor wire is down or input sensor is disconnected (OPEN).

   X2: Remote SV error: communication error of Remote SV master and internal communication / input of master channel is LLLL/HHHH/OPEN when the channel is subjected to display PV.

   X3: An indicator of relative channel flashes.

   After main cause of the error is solved, error status is cleared and the device is returned to the normal operation automatically

## Manuals

For the detail information and instructions, please refer to user manual and user manual for communication, and be sure to follow cautions written in the technical description (catalog, homepage). Visit our homepage (www.autonics.com) to download manuals.

### Cautions during Use

. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents Check the polarity of the terminals before wiring the temperature sensor.

For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire. 3. Keep away from high voltage lines or power lines to prevent inductive noise.

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

4. Do not apply excessive power when connecting or disconnecting the connectors of the product.

5. Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.

Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
 When changing the input sensor, turn off the power first before changing.

After changing the input sensor, modify the value of the corresponding parameter

Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
 Do not overlapping communication line and power line.
 Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect

of external noise.

For accurate temperature measurement, warm up the unit over 20 min after turning on the power. 11. Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device. Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.

12. Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.

- Do not wire to terminals which are not used.
   Install DIN rail vertically from the ground.
- 15. This unit may be used in the following environments ment condition rated in 'Specifications') ②Altitude max. 2,000m ③Pollution degree 2

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