## **Rotary Servomotors**

## SGMEV



## **Model Designations**

## Without Gears

02

Α

Α

2

7th digit

1

**SGMEV**  $\Sigma$ -VSeries Servomotor

**SGMEV** 

1st+2nd digits

6th digit

1st+2nd digits Rated Output

Co	de	Specifications
	01	100 W *
Cubic	02	200 W
form	04	400 W
iomi	08	750 W
	15	1.5 kW
Small	03	300 W **
flange	07	650 W **

\*: Power Supply Voltage 200 VAC only
\*\*: Power Supply Voltage 400 VAC only

#### 3rd digit Power Supply Voltage

Code	Specifications
Α	200 VAC
D	400 VAC

#### 4th digit Serial Encoder

Specifications				
20-bit absolute (standard)				
20-bit incremental (standard)				

#### 5th digit Design Revision Order

Code	Specifications				
Α	IP-55 Standard				
	IP-67 water-proof				
E	specifications				
	(SGMEV-01, 02, 04, 08, 15)				
	Prepared for oil seal				
F	mounting				
	(SGMEV-03, 07)				

#### 6th digit Shaft End

Code	Specifications
2	Straight without key (standard)
4	Straight with key (option)
6	Straight with key and tap (option)
8	Straight with tap (option)

## 7th digit Options

Code	Specifications
1	Without options
С	With holding brake (24 VDC)
E	With oil seal and holding brake (24 VDC)
S	With oil seal

## **Features**

- Low and medium inertia
- Wide selection: 100 W to 1.5 kW capacity, holding brake option
- Mounted serial encoder: 20 bits, high resolution
- Protective structure: Standard protection IP55, expandable to IP67

## **Application Examples**

- Transfer machines
- Material handling machines
- Food processing equipment
- Packaging



SGMEV-03DDA61 (Small flange)

SGMEV-08DDA61 (Cubic form)



### **Ratings and Specifications**

**Time Rating: Continuous** Vibration Class: V15

Insulation Resistance: 500 VDC, 10  $\mbox{M}\Omega$  min.

Ambient Temperature: 0 to 40°C **Excitation:** Permanent magnet Mounting: Flange-mounted Thermal Class: B (130°C)

Withstand Voltage: 1500 VAC for one minute Enclosure: Totally enclosed, self-cooled, IP55 (except for shaft opening)

Ambient Humidity: 20% to 80% (no condensation)

Drive Method: Direct drive

Rotation Direction: Counterclockwise (CCW) with forward run

reference when viewed from the load side

#### 200-V Class

Servomotor Model: SGMEV-		01A	02A	04A	08A	15A	
Rated Output <sup>-1</sup>	kW	0.1	0.2	0.4	0.75	1.5	
Rated Torque*1,*2	Nm	0.318	0.637	1.27	2.39	4.77	
Instantaneous Peak Torque <sup>*1</sup>	Nm	0.955	1.91	3.82	7.16	14.3	
Rated Current*1	Arms	0.89	2.0	2.6	4.1	7.5	
Instantaneous Max. Current 1	Arms	2.8	6.5	8.5	13.9	23.0	
Rated Speed*1	3000						
Max. Speed*1	min <sup>-1</sup>	5000					
Torque Constant	Nm/Arms	0.392	0.349	0.535	0.641	0.687	
Rotor Moment of Inertia	×10 <sup>-4</sup> kgm <sup>2</sup>	0.0491	0.193	0.331	2.10	4.02	
notor Moment of Inertia		(0.0781)	(0.302)	(0.440)	(2.975)	(4.895)	
Rated Power Rate <sup>-1</sup>	kW/s	20.6	21.0	49.0	27.1	56.7	
Rated Angular Acceleration <sup>-1</sup>	rad/s²	64800	33000	38500	11400	11900	
Applicable SERVOPACK	SGDV-	R90A	1R6A	2R8A	5R5A	120A <sup>+3</sup>	

<sup>\*1:</sup> These items and torque-speed characteristics quoted in combination with an SGDV SERVOPACK are at an armature winding temperature of 100°C. Other values quoted are at 20°C.

rack-mounted SERVOPACK model: SGDV-120A \( \square\) A009000). Notes: The values in parentheses are for servomotors with holding brakes.

#### 400-V Class

Servomotor Model: SGMEV-		02D	03D	04D	07D	08D	15D
Rated Output <sup>-1</sup>	kW	0.2	0.3	0.4	0.65	0.75	1.5
Rated Torque*1,*2	Nm	0.637	0.955	1.27	2.07	2.39	4.77
Instantaneous Peak Torque <sup>*1</sup>	Nm	1.91	3.82	3.82	7.16	7.16	14.3
Rated Current*1	Arms	1.4	1.3	1.4	2.2	2.6	4.5
Instantaneous Max. Current <sup>*1</sup>	Arms	4.5	5.1	4.4	7.7	7.8	13.7
Rated Speed*1	min <sup>-1</sup>	3000					
Max. Speed*1	min <sup>-1</sup>	5000					
Torque Constant	Nm/Arms	0.481	0.837	0.963	1.02	0.994	1.135
Rotor Moment of Inertia	×10 <sup>-4</sup> kgm <sup>2</sup>	0.193 (0.302)	0.173 (0.231)	0.331 (0.440)	0.672 (0.812)	2.1 (2.975)	4.02 (4.895)
Rated Power Rate <sup>-1</sup>	kW/s	21.0	52.9	49.0	63.8	27.1	56.7
Rated Angular Acceleration <sup>-1</sup>	rad/s²	33000	55300	38500	30800	11400	11900
Applicable SERVOPACK	SGDV-	1R9D	1R9D	1R9D	3R5D	3R5D	5R4D

<sup>\*1:</sup> These items and torque-speed characteristics quoted in combination with an SGDV SERVOPACK are at an armature winding temperature of 100°C. Other values quoted are at 20°C.

SGMEV-08D, -15D:  $300~\text{mm} \times 300~\text{mm} \times 12~\text{mm}$ Notes: The values in parentheses are for servomotors with holding brakes.

<sup>\*2:</sup> Rated torques are continuous allowable torque values at 40°C with an aluminum heat sink of the following dimensions

SGMEV-01A, -02A, -04A: 250 mm  $\times$  250 mm  $\times$  6 mm

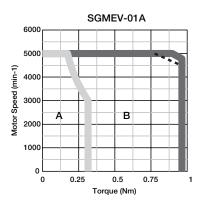
SGMEV-08A, -15A: 300 mm  $\times$  300 mm  $\times$  12 mm

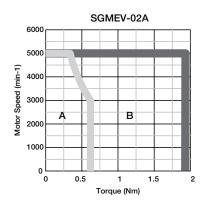
<sup>\*2:</sup> Rated torques are continuous allowable torque values at 40°C with an aluminum heat sink of the following dimensions attached. SGMEV-02D, -03D, -04D, -07D: 250 mm  $\times$  250 mm  $\times$  6 mm

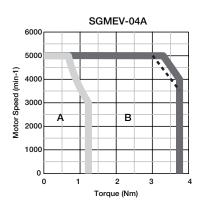
## **SGMEV**

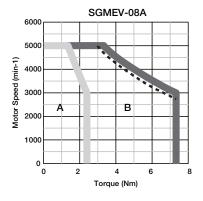
#### **Ratings and Specifications**

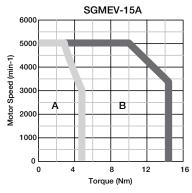
● Torque-Speed Characteristics (200 V/400 V) A: Continuous Duty Zone B: Intermittent Duty Zone

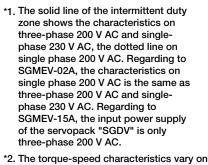


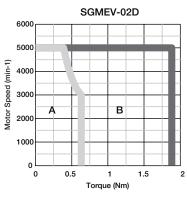


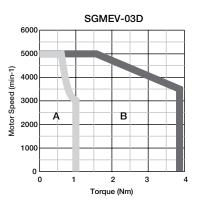


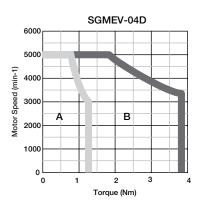




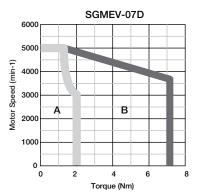


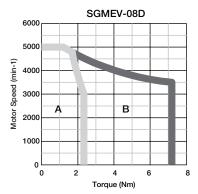


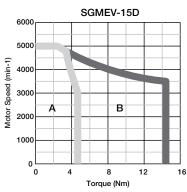




the values of input power supply voltage.







Notes: 1 When the effective torque during intermittent duty is within the rated torque, the servomotor can be used within the intermittent duty zone.

2 When the power cable length exceeds 20 m, note that the intermittent duty zone of the *Torque-Speed Characteristics* will shrink as the line-to-line voltage drops.

## **Ratings and Specifications**

#### Derating values for Servomotor fitted with an Oil Seal

When a motor is fitted with an oil seal, use the following derating rate due to the higher friction torque.

Servomotor Model SGMEV-	01A	02A, 02D	03D	04A, 04D	07D	08A, 08D	15A, 15D
Derating Rate %	9	00			95		

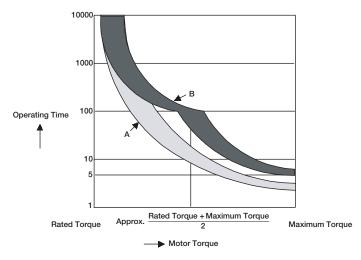
#### Holding Brake Electrical Specifications

	Servomotor	Holding Brake Specifications							
Servomotor	Rated	Holding		Rated Voltage 24 VDC					
Model	Output kW	Torque Nm	Capacity W	Coil Resistance Ohm (at 20°C)	Rated Current A (at 20°C)	Brake Release Time ms	Brake Operation Time ms		
SGMEV-01	0.1	0.318	6	114	0.25				
SGMEV-02	0.2	0.637	5	115	0.21				
SGMEV-03	0.3	0.955	6.9	83.5	0.29				
SGMEV-04	0.4	1.27	7.6	76	0.32	60	100		
SGMEV-07	0.65	2.07	7.7	75.2	0.32	1			
SGMEV-08	0.75	2.39	7.5	76.8	0.31				
SGMEV-15	1.5	4.77	10	57.6	0.42				

Notes: 1 The holding brake is only used to hold the load and cannot be used to stop the servomotor.

#### Overload Characteristics

The overload detection level is set under hot start conditions at a servomotor ambient temperature of 40°C.



Note: Curve A applies to SGMEV motors up to 400 W Curve B applies to motors with a capacity from 650 W up to 1.5 kW

#### Allowable Load Moment of Inertia at the Motor Shaft

The rotor moment of inertia ratio is the value for a servomotor without a gear and a holding brake.

Servomotor	Servomotor Model		Allowable Load Moment of Inertia (Rotor Moment of Inertia Ratio)	
	01A	0.1 kW	25 times	
	02A, 02D	0.2 kW	15 times	
	03D	0.3 kW	20 times	
SGMEV-	04A, 04D	0.4 kW	7 times	
	07D	0.65 kW	20 times	
	08A, 08D	0.75 kW	5 times	
	15A, 15D	1.5 kW	5 times	

<sup>2</sup> The holding brake open time and holding brake operation time vary depending on which discharge circuit is used. Make sure holding brake open time and holding brake operation time are correct for your servomotor.

<sup>3</sup> A 24-VDC power supply is provided by customers.

**SGMEV** 

### Ratings and Specifications

#### Load Moment of Inertia

The larger the load moment of inertia, the worse the movement response.

The allowable load moment of inertia  $(J_L)$  depends on the motor capacity, as shown above. This value is provided strictly as a guideline and results may vary depending on servomotor drive conditions.

Use the AC servo drive capacity selection program SigmaJunmaSize+ to check the operation conditions. The program can be downloaded for free from our web site (http://www.yaskawa.eu.com).

An overvoltage alarm (A.400) is likely to occur during deceleration if the load moment of inertia exceeds the allowable load moment of inertia. SERVOPACKs with a built-in regenerative resistor may generate a regenerative overload alarm (A.320). Take one of the following steps if this occurs.

- Reduce the torque limit.
- Reduce the deceleration rate.
- Reduce the maximum speed.
- Install an external regenerative resistor if the alarm cannot be cleared using the steps above. Regenerative Resistors are not built into 400 W SGDV-2R8 SERVOPACKs.

#### aLLoWaBLE RaDiaL aND THRUST LoaDS

Design the mechanical system so thrust and radial loads applied to the servomotor shaft end during operation fall within the ranges shown in the table.

Servom	otor Model	Allowable Radial Load (Fr) N	Allowable Thrust Load (Fs) N	LF mm	Reference Diagram	
	01A	78	49	20	LF   <del></del>	
	02A, 02D		68	25		
	03D	245	74	30	Fr	
SGMEV-	04A, 04D		68	25	]     Fs	
	07D	200		O.F.	- ·-·-	
	08A, 08D	392	147	35		
	15A, 15D	490		40		

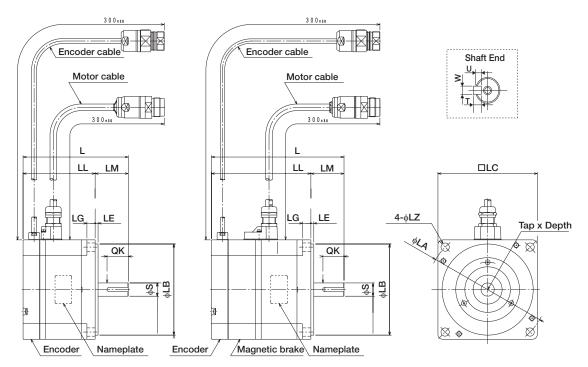
#### Connector Specifications 200-V Class

Servomotor Model SGMEV-	01A	02A, 04A, 08A	15A					
Encoder-end connector	SRUC17GMRWN087							
Pin	021.402.1020							
Manufacturer		Interconnectron						
Servomotor-end connector	SRUC06JMSCN027	SRUC06JMSCN109	SRUC06JMSCN276					
Pin	021.423.1020							
Manufacturer	Interconnectron							

#### Connector Specifications 400-V Class

Servomotor Model SGMEV-	02D, 03D, 04D, 07D, 08D, 15D
Encoder-end connector	SRUC17GMRWN087
Pin	021.402.1020
Manufacturer	Interconnectron
Servomotor-end connector	LRRA06AMRPN182
Pin	021.279.1020
Manufacturer	Interconnectron

## External Dimensions SGMEV-02D, -04D, -08D, -15D Units: mm



Models without Brake

Models with Brake

Model SGMEV-	L	LL	LM	Flange Face Dimensions						Shaft End Dimensions					Approx. Mass	
SGIVIEV-				LA	LB	LC	LE	LG	LZ	S	QK	W	Т	U	Tap x Depth	kg
02D A61 (02D A6C)	97 (128.5)	67 (98.5)	30	90	70 <sup>0</sup> -0.030	80	3	8	7	14 <sup>.0</sup>	16					1.4 (1.9)
04D A61 (04D A6C)	117 (148.5)	87 (118.5)	30	90	70 <sub>-0.030</sub>	80	3	0	,	14-0.011	10	5	5	3	M5 x 8L	2.1 (2.6)
08D□A61 (08D□A6C)	126.5 (160)	86.5 (120)	40	145	440 0	120	3.5	10	10	16.0.011	22					4.2 (4.7)
15D A61 (15D A6C)	154.5 (188)	114.5 (148)	40	145	110 -0.035	120	3.5	10	10	19 <sup>.0</sup>	22	6	6	3.5	M6 x 10L	6.6 (8.1)

Note: The models with oil seals are of the same configuration.

The models and values in parentheses are for servomotors with holding brakes.

• Cable Specifications for Encoder-end Connector

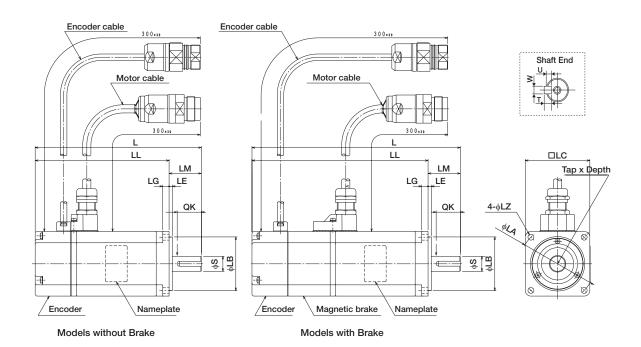


Pin No.	Description	Colour				
1	0 V (Battery)	Orange/White				
2	3.6 V (Battery)	Orange				
3	Data +	Blue				
4	Data -	Blue/White				
5 - 7	Free	-				
8	+ 5 V (Power Supply)	Red				
9	0 V (Power Supply)	Black				
10 - 17	Free	-				
Connector Case	Frame ground	Shield wire				

• Cable Specifications for Servomotor-end Connector



Pin No.	Description	Colour				
1	Phase U	Red				
2	Phase V	White				
4	Phase W	Blue				
5, 6	Brake and/or Free	Black				
<b>+</b>	Frame ground	Green/Yellow				



Model SGMEV-	L	LL	LM		Flange F	ace D	imensi	ons			Sh	aft End	d Dime	nsions	;	Approx. Mass
SGIVIEV-				LA	LB	LC	LE	LG	LZ	S	QK	W	Т	U	Tap x Depth	kg
03D□A61 (03D□A6C)	154.5 (194)	124.5 (164)	30	70	50 <sub>-0.025</sub>	60	3	6	5.5	<b>14</b> <sup>0</sup> <sub>-0.011</sub>	20	5	_	,	M5 x 8L	1.7 (2.2)
07D□A61 (07D□A6C)	185 (229.5)	145 (189.5)	40	90	70 -0.025	80	3	8	70	16 -0.011	30	5	5	3	INIO X OL	3.4 (4.3)

Note: The models with oil seals are of the same configuration.

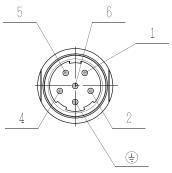
The models and values in parentheses are for servomotors with holding brakes.

• Cable Specifications for Encoder-end Connector



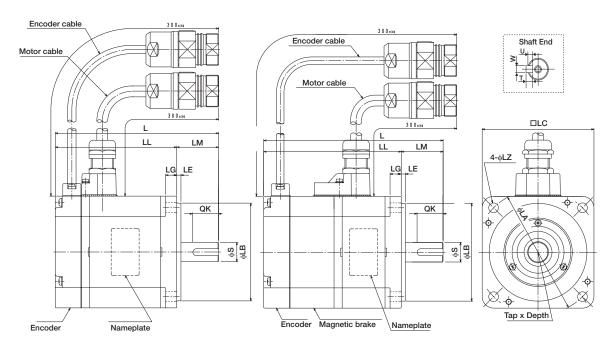
Pin No.	Description	Colour				
1	0 V (Battery)	Orange/White				
2	3.6 V (Battery)	Orange				
3	Data +	Blue				
4	Data -	Blue/White				
5 - 7	Free	-				
8	+ 5 V (Power Supply)	Red				
9	0 V (Power Supply)	Black				
10 - 17	Free	-				
Connector Case	Frame ground	Shield wire				

#### Cable Specifications for Servomotor-end Connector



Pin No.	Description	Colour				
1	Phase U	Red				
2	Phase V	White				
4	Phase W	Blue				
5, 6	Brake and/or Free	Black				
(1)	Frame ground	Green/Yellow				

## External Dimensions SGMEV-01A, -02A, -04A, -08A, -15A Units: mm



Models without Brake

Models with Brake

Model	L	LL	LM		Flange Face Dimensions						Shaft End Dimensions						
SGMEV-				LA	LB	LC	LE	LG	LZ	S	QK	W	Т	U	Tap x Depth	kg	
01A□A61 (01A□A6C)	87 (116)	62 (91)	25	70	50 <sub>-0.030</sub>	60	3	6		8 -0.011	14	3	3	1.8	M3 x 6L	0.7 (0.9)	
02A□A61 (02A□A6C)	97 (128.5)	67 (98.5)	30	00	70.0	80	•		7	440	16					1.4 (1.9)	
04A□A61 (04A□A6C)	117 (148.5)	87 (118.5)	30	90	70 -0.030	80	6	8	/	14 <sup>0</sup> <sub>-0.011</sub>	16	5	5	3	M5 x 8L	2.1 (2.6)	
08A□A61 (08A□A6C)	126.5 (160)	86.5 (120)	40	145	1100	120	3.5	10	10	16 0 -0.011	22					4.2 (4.7)	
15A□A61 (15A□A6C)	154.5 (188)	114.5 (148)	40	140	110 -0.035	120	ა.5	10	10	19 0 -0.013	22	6	6	3.5	M6 x 10L	6.6 (8.1)	

Note: The models with oil seals are of the same configuration.

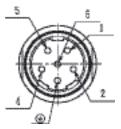
The models and values in parentheses are for servomotors with holding brakes.

• Cable Specifications for Encoder-end Connector



Pin No.	Description	Colour				
1	0 V (Battery)	Orange/White				
2	3.6 V (Battery)	Orange				
3	Data +	Blue				
4	Data -	Blue/White				
5 - 7	Free	-				
8	+ 5 V (Power Supply)	Red				
9	0 V (Power Supply)	Black				
10 - 17	Free	-				
Connector Case	Frame ground	Shield wire				

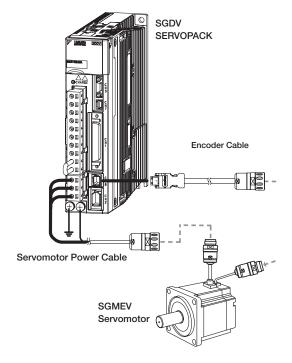
• Cable Specifications for Servomotor-end Connector



Pin No.	Description	Colour
1	Phase U	Red
2	Phase V	White
4	Phase W	Blue
5, 6	Brake and/or Free	Black
<b>(±)</b>	Frame ground	Green/Yellow

## Selecting Cables (SGMEV 200-V Class)

- Cables Connections
- Standard Wiring (Max. encoder cable length: 20 m)



## **A**CAUTION

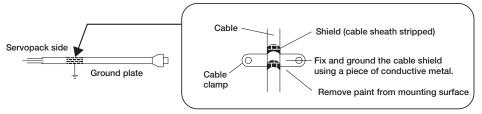
- •Separate the servomotor power cable wiring from the I/O signal cable and encoder cable at least 30 cm, and do not bundle or run them in the same duct.
- •When the power cable length exceeds 20 m, note that the intermittent duty zone of the Torque-Speed Characteristics will shrink as the line-to-line voltage drops.

#### Servomotor Power Cable

Servomotor Rated	Name	Longith	Order No.	- Specifications					
Output	Name	Length	Flexible Type*	эреспісацопа					
		03 m	DP9325252-3G						
	For Servomotor without	05 m	DP9325252-5G						
	Holding Brakes	10 m	DP9325252-10G						
	Troiding Brakes	15 m	DP9325252-15G						
0.1 kW		20 m	DP9325252-20G						
0.75 kW		03 m	DP9325253-3G						
	For Servomotor with Holding Brakes	05 m	DP9325253-5G						
		10 m	DP9325253-10G						
		15 m	DP9325253-15G						
		20 m	DP9325253-20G						
		03 m	DP9325254-3G						
	For Servomotor without	05 m	DP9325254-5G						
	Holding Brakes	10 m	DP9325254-10G						
	Training Branco	15 m	DP9325254-15G						
1.5 kW		20 m	DP9325254-20G						
1.0 KVV		03 m	DP9325255-3G						
	For Servomotor with	05 m	DP9325255-5G						
	Holding Brakes	10 m	DP9325255-10G						
	Troiding Branco	15 m	DP9325255-15G						
		20 m	DP9325255-20G						

#### • Encoder Cables (Max. length: 20 m)

Name	Length	Order No.	Specifications	
		Flexible Type		
Cables with Connectors on both sides	3 m	DP9325256-3G		
	5 m	DP9325256-5G		
	10 m	DP9325256-10G		
	15 m	DP9325256-15G		
	20 m	DP9325256-20G		



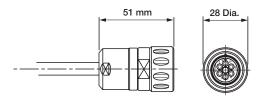
#### Connectors

Specification	Model
Hypertac power connector IP67 for 200 VAC SGMEV motors	SPOC-06K-FSDN169
Hypertac encoder connector IP67 for SGMEV motors	SPOC-17H-FRON169
Spare part, Hypertac power connector male for 200 V motors (included with SGMEV motors)	SRUC-06J-MSCN236
Spare part, Hypertac encoder connector male (included with SGMEV motors)	SRUC-17G-MRWN087

#### Specification of Motor Connector

• Motor Connector (cable side) with Ground connection

Part-No.	Plug with Cable Clamp			
S PU C 06J MS CN 236	Cable diam. 7 mm			
S PU C 06J MS CN 020	Cable diam. 9,5 mm			
Reference: Original Yaskawa lead				



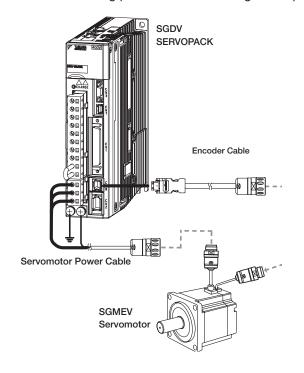
Specifications			
Poles	6		
Temperature Range	-25°C up to 125°C		
Cable Clamp	shown in table		
Type of protection	IP67 connected IP00 not connected		
Electrical Performance			
Current Rating	15A, environmental temperature 60°C		
Max. Current	23 A cyclic (5 sec on, 10 sec out)		
Voltage Rating	250 V		
Test Voltage	4000 V		
Contact Resistance	< 5 mOhm		
Mating Cycles	> 500		
Materials			
Body	PA 6.6, glass-fiber reinforced		
Insulator	Peek		
Contacts	Brass / Gold plated		
Seals	FPM		
Contacts			
Туре	Pin diam. 2		
Part-No.	021.421.1020		
Termination	solder cup		
Latch Retention	> 35 N		

Note: Specification in accordance with VDE 0110/0627 - Contamination Level: 3 Excess voltage category: 3 - Installation altitude < or = 4000 m

## Selecting Cables (SGMEV 400-V Class)

#### Cables Connections

• Standard Wiring (Max. encoder cable length: 20 m)



## **A**CAUTION

- Separate the servomotor power cable wiring from the I/O signal cable and encoder cable at least 30 cm, and do not bundle or run them in the same duct.
- •When the power cable length exceeds 20 m, note that the intermittent duty zone of the Torque-Speed Characteristics will shrink as the line-to-line voltage drops.

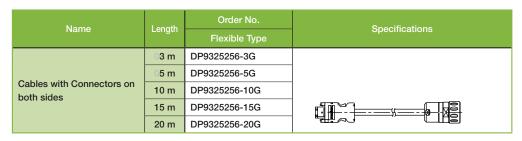
#### Servomotor Power Cable

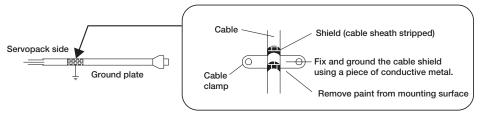
Servomotor	Servomotor Rated Name		Order No.	Specifications
Output		Length -	Flexible Type*	
		03 m	JZSP-CMM20D15-03G	
		05 m	JZSP-CMM20D15-05G	
	For Servomotor without Holding Brakes	10 m	JZSP-CMM20D15-10G	
Tiolding brakes	Tiolang Brakes	15 m	JZSP-CMM20D15-15G	© <del>=</del>
0.2 kW	0.2 kW 1.5 kW For Servomotor with Holding Brakes	20 m	JZSP-CMM20D15-20G	
1.5 kW		03 m	JZSP-CMM30D15-03G	
		05 m	JZSP-CMM30D15-05G	
		10 m	JZSP-CMM30D15-10G	
		15 m	JZSP-CMM30D15-15G	
		20 m	JZSP-CMM30D15-20G	

<sup>\*:</sup> These flexible cables are provided as standard equipment. Note: Cables without connectors can be ordered on request.

## Selecting Cables (SGMEV 400-V Class)

#### • Encoder Cables (Max. length: 20 m)



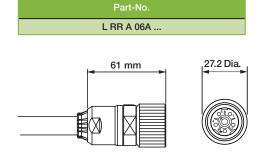


#### Connectors

Specification	Model
Hypertac power connector IP67 for SGMEV motors	LPRA-06B-FRBN170
Hypertac encoder connector IP67 for SGMEV motors	SPOC-17H-FRON169
Spare part, Hypertac power connector male for 400 V motors (included with SGMEV motors)	LRRA-06A-MRPN182
Spare part, Hypertac encoder connector male (included with SGMEV motors)	SRUC-17G-MRWN087

#### Specification of Motor Connector

• Motor Connector (cable side) with Ground connection



Specifications				
Poles	6 (5 + PE)			
Temperature Range	-40°C up to 125°C			
Cable Clamp	not applicable			
Type of protection	IP67 connected			
Type of protection	IP00 not connected			
Electric	cal Performance			
Current Rating	20 A			
Voltage Rating	250 V			
Test Voltage	4000 V			
Contact Resistance	< 3 mOhm			
Mating Cycles	> 500			
Materials				
Body	Brass / Nickel plated			
Insulator	PA 6.6			
Contacts	Brass / Nickel plated			
Seals	FPM			
	Contacts			
Туре	Pin diam. 2 mm			
Part-No.	021.279.1020			
Termination	crimp; 0.4 to 2.5 mm <sup>2</sup>			
Latch Retention	> 40 N			
Tools				
Crimping Tool	B 151; B 179			
Positioner	B 165			
Contact Insertion	B 117			
Contact Removal	B 037 A			

Note: Specification in accordance with VDE 0110/0627 - Contamination Level: 3 Excess voltage category: 3 - Installation altitude < or = 4000 m

**SGMEV** 

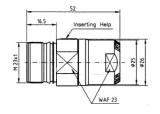
# RIES Σ-V SERIES Σ-V SERIES

## Selecting Cables (SGMEV 200-V and 400-V Class)

#### Specification of Encoder Connector

• Encoder Connector (Encoder side)







Specifications					
Poles	17				
Temperature Range	-25°C up to 125°C				
Cable Clamp	diam. 5.5 mm				
Type of protection	IP67 connected IP00 not connected				
	Electrical Performance				
Current Rating	9 A				
Voltage Rating	20 V				
Test Voltage	800 V				
Contact Resistance	< 5 mOhm				
Mating Cycles	> 500				
	Materials				
Body	PA 6.6 glass-fiber reinforced				
Insulator	PBT, glass-fiber reinforced				
Contacts	Brass / Gold plated				
Seals	FPM				
Contacts					
Туре	Pin diam. 1 mm	Pin diam. 1 mm			
Part-No.	021.311.1020	021.402.1020			
Termination	crimp; 0.24 to 1.0 mm <sup>2</sup>	crimp; 0.05 to 0.34 mm <sup>2</sup>			
Latch Retention	> 30 N	> 30 N			

Note: Specification in accordance with VDE 0110/0627 - Contamination Level: 3 Excess voltage category: 3 - Installation altitude < or = 4000 m  $\,$